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Attitude determination by integration of mems

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Patent us6553299 - methods and apparatus for

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A technical review on navigation systems of

(laser positioning, millimeter wave radar), and local feature autonomous row crop cultivation agricultural real time autonomous

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Autonomous time- frequency cropping and feature-

Three autonomous cropping and feature extraction algorithms are examined that can be used for classification of low probability of intercept radar modulations using

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Autonomous Time-Frequency Morphological Feature Classification results for five simulated radar modulations are shown to demonstrate the feature extraction

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